

## Diverse motions

Human / Sharpa / Wuji2  
Posture and interaction

## Pose manifold

Structure and coverage  
Representative candidates

## Physical RL

Reference-conditioned teacher  
Successful interactions

## Skill distillation

Cluster / Joint / Fingertip  
Hybrid commands

## Agent toolkit

Retrieve → invoke → observe  
30 Hz hand control

STRUCTURED CANDIDATES → VERIFIED PHYSICAL BEHAVIOR → CALLABLE FEEDBACK CONTROL